

# Dynamic Tracing in Userspace

### Dyninst, Kaji and the way ahead..

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## Agenda

### Recap

• Questions raised

### Investigations

- How Dyninst + UST performs
- A separate dynamic tracing lib Kaji
- Analysis of Dyninst and Kaji

### What Next

- Further investigations
- New features



The goal was to investigate tools which can be of use to provide dynamic tracing with UST without compromising performance

### Questions raised :

- How well would Dyninst perform?
- What does it actually do?
- Is GDB's infrastructure better than Dyninst?
- Are there new ways to leverage the current tools?



## **Dyninst + UST**





Target binary is first started and then mutated in process



**Dyninst + UST** 



Dyninst+UST provides similar overhead as compared to static tracing. Good scalabilitywhen tuned with right options (disable recursive trampoline check and disable FPR save)

## Kaji

- A new lightweight library for dynamic tracing in development
- We used GDB's jump-pad based approach very minimal
- At a very nascent stage more like a proof of concept for now

*Zifei's repo :* https://github.com/5kg/kaji *My repo :* https://github.com/tuxology/kaji



### Dyninst and Kaji Analysis

#### #### Original ###

4009e8	<+0>:	push	%гbр
4009e9	<+1>:	MOV	%гѕр,%гbр
4009ec	<+4>:	movl	\$0x2a,-0x4(%rbp)
4009f3	<+11>:	рор	%гbр
4009f4	<+12>:	retq	

# Target function was dynamically

 instrumented with a tracepoint call and observed

#### #### Dyninst's Modification ###

400	09e8 <+0>:	jmpq	0×10000
10	hee	rex.RB	cld
	olock replaced	sub	(%rax),%al
400	09f1 <+9>:	add	%al,(%rax)
400	09f3 <+11>:	рор	%гbр
400	09f4 <+12>:	retq	

#### ##### Kaji's Modification ###

Jump at		push	%гbр	
instruction > 5byte	e	MOV	%гѕр,%гbр	
400aa4 <+4>:		jmpq	0×100000	
400aa9 <+9>:		add	%al,(%rax)	
400aab <+11>	•	рор	%гbр	
400aac <+12>	•	retq	1	ŀ
		N		

## Investigations \_\_\_\_

Dyninst' s	Jun	Out of line execut	ion		Grow stack	
0×10000:	push	%гbр	0x1003d:	lea	-0x18(%rsp	),%rsp
0x10001:	MOV	%гѕр,%гbр	0x10042:	movabs	\$0x601064,	%гах
0×10004:	movl	\$0x2a,-0x4(%rbp)	0x1004c:	MOV	(%rax),%ec	li
0x1000b:	рор	%гbр	$0 \times 100 4 \circ \cdot$	movabs	\$0x0,%rax	var = 43
Trampoline start	lea	-0xa8(%rsp),%rsp	tracepoint lib	movabs	\$0x7f44892	8fa06,%rbx
Grow stack	MOV	%rax,0x20(%rsp)	0x10062:	callq	*%rbx	
0×10019:	lea	0xa8(%rsp),%rax	0x10064:	lea	0x18(%rsp)	,%гѕр
Do some tricks	and	\$0xffffffffffffffe0,%rsp	0x10069:	рор	%г15	Shrink stack
0x10025:	MOV	%rax,(%rsp)	Pop regs	рор	%г14 -	
0x10029:	MOV	-0x88(%rax),%rax	0x1006d:	рор	%г13	
Push reas	push	%гах	0x1006f:	рор	%г12	
	push	%гbх	0x10071:	рор	%rsp	
0x10032:	push	%гсх	0x10072:	рор	%rdx	
0x10033:	push	%rdx	0x10073:	рор	%гсх	Restore
0x10034:	push	%гѕр	0x10074:	рор	%rbx or	igninal rsp
0x10035:	push	%г12	0x10075:	рор	%гах	
0x10037:	push	%г13	0x10076:	mov	(%rsp),%rs	P A
0x10039:	push	%г14	0x1007a:	retq		
0x1003b:	push	%r15				

## Kaji' s Jump

					••		 	
		push	%гах		0	x100027:	рор	%rdx
	0/100001.	push	%г8		0	x100028:	рор	%гсх
ł	0x100003:	push	%г9		0	×100029:	рор	%г9
j	0x100005:	push	%гсх		0	x10002b:	рор	%г8
	0x100006:	push	%rdx		Exec	ute displaced	рор	%гах
1	0x100007:	push	%rsi		in	structions	movl	\$0x2a,-0x4(%rbp)
j	0x100008:	push	%гѕр		0	x100035:	 jmpq	0x400aab <do_stuff+11></do_stuff+11>
ļ	0x100009:	push	%г12					
j	0x10000b:	push	%г13					Go back from
	0x10000d:	push	%г14					Jump-pad
	0x10000f:	push	%г15					
	0x100011:	movabs	\$0x7f654	32сb472,%га	ах			
		callq	*%гах					
		рор	%г15	kaji_int_p	robe()			
j	0x10001f:	рор	%г14					
j	0x100021:	рор	%г13					
	0x100023:	рор	%г12					
	0x100025:	рор	%гѕр					
	0x100026:	рор	%rsi				l),	
	*						· · · · · · · · · · · · · · · · · · ·	

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### Kaji/Dyninst + UST (Overhead & Scalability)



As expected, the similarity in both approaches translates to similar performance. But hold on...

### Kaji/Dyninst + UST (Startup)



#### Dyninst

	-	
п	T <sub>instr</sub> (S)	T <sub>reg</sub> (S)
1	2.63	0.03
10	2.65	0.03
100	2.99	0.04
1000	6.68	0.05
5000	35.03	0.11

Measure  $\mathbf{T}_{reg} + \mathbf{T}_{instr}$ with *n* varying from 1 to 5000

(for Kaji, n is restricted to 1 as its not mature enough to handle multiple tracepoints for now )

	Kaji	
n	T <sub>instr</sub> (s)	T <sub>reg</sub> (s)
1	0.002	0.012

Even for *n*=1, instrumentation cost for Kaji is way less (**0.002s** compared to **2.63s** for Dyninst) as we can have fine grained control of instrumentation time unlike Dyninst.

## What Next?

### More analysis!

One does not simply... stop analyzing stuff!

- Real-life benchmarks
  - PostgreSQL, MariaDB, Kenrel build Mimic multiple static tracepoints but build and instrument them dynamically
- Isolate startup time for multiple scenarios with a real life benchmarks

### **Possible features**

- On-the-fly dynamic tracepoints
  - Generate dynamic tracepoints based on user inputs scripts, switches
  - *Zifei's* early implementation (expand the macro strategy) http://ur1.ca/g5w27
- Fixed type dynamic tracepoints
  - Common tracepoints based on types regs, ints, floats, strings
  - Easy access, no need to generate separate tracepoints

## What Next?

### **Further investigation**

- Use of bytecode interpreters and JIT in tracing infrastructure
  - Can be useful for various features LTTng already has bytecode interpretation for implementing filters
  - Ktap uses bytecode based dynamic tracing for kernel
- Can this lead to a purely userspace based bytecode tracing design?
- Seccomp-bpf syscall filtering using BPF for sandboxing.
  - Chrome is already using that.
  - A step further libseccomp has provision to output BPF code
- JIT for BPF improves the performance further. Should we aim for a similar approach?



# Questions?

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